Instructions of Use

## DIGEM $96 \times 48$ CK5

## Digital panel meter 96x48 A1265


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## Notes and Warnings

This instrument has been shipped from the factory in proper condition for safe operation. In order to maintain this condition and to assure safe operation, the user must observe all notes and warnings included in these operating instructions. If damage to the instrument causes any doubt concerning safe operation, it must be taken out of service. Visible damage always represents cause for such doubt. Prior to initial start-up it must be determined, whether or not the measuring instrument is equipped for the proposed application (correct supply voltage, inputs and outputs). The model of the instrument and possible options are identified on the serial plate. When covers are opened or components are removed, voltage conducting parts may be exposed. Balancing, maintenance or repair of an open, live instrument may only be carried out by trained personnel who are familiar with the dangers involved.

## 1 Applications

This measuring instrument is suited for applications in which the monitoring and evaluation of measurement values are required, which, if applicable, must also be transmitted via analog outputs or a serial interface.

## 2 Installation

First push the instrument into the switch panel without screw clips. The screw clips are then set into the cone-head rivets at the side panels. The instrument can then be tightened to the switch panel with the screws. For installation into a grid mounting system, the fastening elements designed especially for the grid system in use are set into the cone-head rivets. The complete instrument can then be inserted into the grid system.


Attention!
If several devices are installed with maximum component density it must be observed, that the allowable operating temperature of $50^{\circ} \mathrm{C}$ is not exceeded despite specific heat.

Dimensional drawing with switch panel opening: $45^{+0.6} \times 92^{+0.8} \mathrm{~mm}$


## 3 Connection

### 3.1 Supply Voltage


3.2 Measurement Input (per Model)

| Model | Ranges | Connector Pin Assignment |
| :---: | :---: | :---: |
| DC | $\mathrm{V}, \mathrm{mV}$, mA |  |
| AC | V , mA |  |
| AC True RMS | $200 \mathrm{~V}, 700 \mathrm{~V}$ | $\square$ |
| Line Frequency | $\begin{aligned} & \text { for AC-V } \\ & (80 \mathrm{~V}-500 \mathrm{~V}) \end{aligned}$ | $123456$ |
| DC with power supply for 2-wire transducer | mA | + - Measurement Input |
| AC | A |  |
| AC True RMS | $\begin{aligned} & \mathrm{A} \\ & \mathrm{~mA} \end{aligned}$ |  |
| AC True RMS | 200 mV -20V |  |
| Temperature Measurement with Thermocouples | all |  |


| Model | Ranges | Connector Pin Assignment |
| :---: | :---: | :---: |
| Temperature Measurement with PT100 | all |  |
| Resistance Measurement | all |  |
| Frequency Measurement, Counter | all |  |
| R.P.M. Measurement | all |  |
| DC with <br> 2 Measurement Inputs |  |  |


| Model | Ranges | Connector Pin Assignment |
| :---: | :---: | :---: |
| Pressure Measurement | all |  |
| Pressure Measurement with Automatic Calibration | all |  |

3.3 Limit Value Outputs (Option)


### 3.4 Analog Output (Option)



Attention!
Terminals 8, 910 and 11 are electrically connected to the measurement input. Isolation of external circuit elements must be executed in a fashion suitable for the prevailing measurement input potential.

## Instrument Test (Test)

When terminals 10 and 11 are bridged, the entire display is darkened.
Attention: This connection causes resetting of the microprocessor. All stored min. and max. values, as well as automatic tare values, are lost.
After this connection is interrupted, a seg-
 ment test is conducted for about 1 second.
Thereafter, the instrument returns to normal operation.
Display Storage (Hold)
When terminals 9 and 11 are bridged in the normal display mode, the currently displayed value is stored. This has no influence on the measuring sequence.
In the counter mode, this causes setting of the counter to zero. In the tare mode the tare zero-value is set.

## Program Protection (Lock)

When terminals 8 and 11 are bridged, the limit values selected before adjustment are protected and the programming of important parameters is disabled. If an attempt is made to change the protected limit values selected prior to adjustment, the message "Loc" appears in the display.
3.6 Serial Interface (Option)

Connector Pin Assignment


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A connector cable is included with measuring instruments with serial interface.

| Panel Meter RJ 11 Socket |  |  | Panel Meter Cable, <br> 9 Pole Sub-D |  | PC Configuration, 9 Pole |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | RS232 | RS485 | RS232 |  | RS232 |  |
| Pin 3 | RxD | B (low) | Pin 3 | RxD | Pin 3 | TxD |
| Pin 4 | TxD | A (high) | Pin 2 | TxD | Pin 2 | RxD |
| Pin 5 | +5V | +5V | Pin 7 | blank | Pin 7 |  |
| Pin 6 | Ground | Ground | Pin 5 | Ground | Pin 5 | Ground |

## 4 Operation

The measuring instrument displays the current measurement value. Zeros which precede the decimal point are not displayed. Depending upon instrument configuration, one or another of the parameters is removed. The following are a few of the important instrument configurations:

- Limit value relays: 2 or 4 relays, each with min-min, max-max or min-max contacts
- Minimum value panel meter
- Maximum value panel meter
- Min. max. value storage
- Alarm storage
4.1 Limit Values $(\operatorname{cod} 2=x(4.7) x)$

The instrument can be used as a MESSCONTACTER, if limit value relays are used (option).
For programming of parameters see table on page 12.


Read-out of selected limit values and minimum and maximum measurement values
Depending on the model, either 2 or 4 limit values can be digitally selected. The limit values LOL1, LOL2 and HIL1, and HIL2 function either as min-max, min-min or max-max contacts, depending upon the selected function.
Depending upon the selected function, the relays work either according to the principle of bias current or load current. If no special particulars are included concerning the type of contacts, and if these are not indicated on the serial plate, the measuring instrument has been laid out at the factory with min-max contacts for load current. Instrument settings cannot be changed when it is installed. Corresponding instructions are described in programming for cod2 (see table on page 13).


Setting limit values
Attention: If the Loc message blinks at the beginning of limit value setting, the limit values are protected against change.
Each limit value is stored with P , and the preset value for the subsequent limit value is then displayed in blinking fashion.

## Saving Limit Values

The limit values can be protected against change in two ways.

## Attention!

This work may only be carried out by a trained electrician. The pc board accessed during this work is live.

- By bridging terminals 8 and 11 at the rear of the instrument (see chap. 3.5 page 7 ).
- With a coding switch in the instrument.

To this end remove the front frame, the front plate and the front panel. Two coding switches are located at the right of the display. In order to lock in the limit values, push the lower switch to the left. The limit values are thus protected against change.

4.2 Minimum Value Panel Meter $(\operatorname{cod} 2=x 1 x)$

As a rule, the instrument always displays the minimum measurement value.
Current and maximum measurement values are read as follows:

| Display | Key Sequence |
| :--- | :--- |
| Min. Measurement Value |  |
| Current Measurement Value | P |
| Max. Measurement Value | $\Uparrow$ |
| Delete Min. Measurement Value (re-enable) | first press $\Downarrow$ and then press $\uparrow$ and $\downarrow$ simultaneously |

### 4.3 Maximum Value Panel Meter $(\operatorname{cod} 2=x 2 x)$

As a rule, the instrument always displays the maximum measurement value. Current and minimum measurement values are read as follows:

| Display | Key Sequence |
| :--- | :--- |
| Max. Measurement Value |  |
| Current Measurement Value | press P continuously |
| Min. Measurement Value | $\Downarrow$ |
| Delete Max. Measurement Value (re-enable) | first press $\Uparrow$ and then press $\Uparrow$ and $\downarrow$ simultaneously |

### 4.4 Resetting Min. and Max. Display Values

Press keys $\Uparrow$ and $\Downarrow$ simultaneously.

### 4.5 $\quad$ Min-Max Storage $(\operatorname{cod} 2=x 0 x)$

The instrument always displays the current measurement value. Minimum and maximum measurement values are read as follows and deleted:

| Display | Key Sequence |
| :--- | :--- |
| Current Measurement Value | $\Downarrow$ |
| Min. Measurement Value | $\Uparrow$ |
| Max. Measurement Value | press $\Uparrow$ or $\Downarrow$ and then press $\Uparrow$ and $\downarrow$ simultaneously |
| Delete Min. or Max. Measurement Value <br> (re-enable) | P (at each level) |
| Return to Current Measurement Value |  |

### 4.6 Panel Meter with Automatic Tare $(\operatorname{cod} 3=3 x x)$

With this model the first measured value is stored. The measuring instrument determines the difference between the current measurement value and the stored value (tare value) for each subsequent measurement. The difference between these values is displayed. The right decimal point lights up.

| Display | Key Sequence |
| :--- | :--- |
| Current Differential Value | P |
| Store Tare Value | press $\Uparrow$ and $\downarrow$ simultaneously |
| Delete Tare Value |  |

The tare value is deleted after display storage is ended (pins 9 and 11 chap. 3.5 page 7). The right decimal point is no longer lit up if no tare value is in storage.

### 4.7 Switching Hysteresis and Delay Time (Option)

The measuring instrument can be programmed with either a switching hysteresis or a delay time for the alarm message or the relays. Switching hysteresis can be adjusted from $\pm 1$ D to $\pm 127$ D. A delay between 0 and 127 s can be selected. Instructions for programming can be found in chap. 5.7 page 19.

### 4.8 Alarm Storage (Option)

If the measurement value is within the alarm range, an alarm message is continuously displayed. When the measurement value is no longer within the alarm range, the alarm message is normally deactivated. If this is not desired, the instrument can be programmed for alarm storage. This function stores the alarm message until it is deleted with the $\Uparrow$ and $\Downarrow$ keys, or with an external signal at the hold input. Alarm storage programming is described in chap. 5.7 page 19.

### 4.9 Automatic Balancing for Pressure Measurements (Option)

If balancing of the zero point and the final value is frequently required during operation, the measuring instrument can be programmed for automatic balancing (see table on page 13, parameter $\operatorname{cod} 3,1^{\text {st }}$ digit).
If this function is activated, automatic balancing is activated by pressing and holding the $P$ key for 2 seconds.
ZEro and a digit blink alternately at the measuring instrument. The input magnitude which corresponds to the value of the blinking digit must be applied to the measurement input. The measuring instrument automatically balances the input magnitude to the digit, which blinks alternately with ZEro. The value can be changed with the $\Uparrow$ and $\downarrow$ keys, to which balancing is to be carried out. If the $P$ key is pressed repeatedly, SPAn and a digit blink alternately. The input magnitude which corresponds to the value of the blinking digit must be applied to the measuring instrument. When the $P$ key is pressed again, the new values are stored and remain even in the event of power failure.

## Pressure Measurement, Special Case

For pressure measurements with Autocal, automatic balancing is accomplished by pressing and holding the P key for approximately 8 seconds.

## 5 Instrument Settings

### 5.1 Significance of Parameters and Programming Instructions

 Instrument settings include the following parameters:| Parameter | Function | Setting Range |
| :---: | :---: | :---: |
| bri | Display brightness | $0 . . .7$ |
| hCA | Initialize Hardware Calibration |  |
| ZEro | Measuring range, lower limit | -19,999 ... 32,765 |
| SPAn | Measuring range, upper limit | -19,999 ... 32,765 |
| PCA | Initialize Software Calibration |  |
| OFSt | Offset adjustment | -19,999 ... 32,765 |
| SCAL | Measurement value multiplier | -1.9999 ... 1.9999 |
| Adr | Serial interface address | 0 ... 255 |
| bAud | Transmission speed | 200 ... 19,200 |
| cod 1 (display) | $\begin{array}{\|ll\|} \hline 1^{\text {st }} \text { digit: } & \text { LED limit values and indication of tendency } \\ 2^{\text {nd }} \text { digit: } & \text { decimal point } \\ 3^{\text {rd }} \text { digit: } & \text { rounding of the last place } \\ \hline \end{array}$ | $\begin{aligned} & 0 \ldots 3 \\ & 0 \ldots 7 \\ & 0 \ldots . .7 \end{aligned}$ |
| $\begin{aligned} & \hline \text { cod } 2 \\ & \text { (limit values) } \end{aligned}$ | $\begin{array}{\|ll} 1^{\text {st }} \text { digit: } & \text { blinking display for alarm message } \\ 2^{\text {nd }} \text { digit: } & \text { storage of min-max value, } \\ & \text { limit values function } \\ 3^{\text {rd }} \text { digit: } & \text { switching hysteresis, } \\ & \text { delay time } \\ & \text { and alarm storage } \end{array}$ | $\begin{aligned} & 0 . . .3 \\ & 0 . . .7 \\ & 0 \ldots .7 \end{aligned}$ |
| cod 3 (special display functions) | $\begin{array}{\|ll\|} \hline 1^{\text {st }} \text { digit: } & \cos \varphi \text { function, } \\ \text { automatic tare and automatic balancing } \\ 2^{\text {nd }} \text { digit: } & \text { analog output balancing } \\ 3^{\text {rd }} \text { digit: } & \text { determination of mean value } \\ \hline \end{array}$ | $\begin{array}{\|l\|} 0 \ldots 3 \\ 0 \ldots . .7 \\ 0 \ldots . .7 \end{array}$ |
| $\operatorname{cod} 4$ <br> (measurement <br> functions) | $\begin{array}{ll} 1^{\text {st }} \text { digit: } & \text { measurement speed, } \\ \text { analog or digital measurement input } \\ 2^{\text {nd }} \text { digit: } & \text { linear/non-linear meas. input, remote display } \\ 3^{\text {rd }} \text { digit: } & \text { arithmetic linking of two inputs, } \\ & \text { temp. sensor, frequency measurement range } \\ \hline \end{array}$ | $\begin{array}{\|l\|l} 0 \ldots 3 \\ 0 \ldots . & 7 \\ 0 \ldots . & 7 \end{array}$ |

Functions can only be programmed, when the internal program switch is set to the corresponding position.
$3^{\text {rd }}$ digit means: the outside right hand display segment.

Detailed Representation of Parameter cod1 to cod4


| $\operatorname{cod} 4$ | 1 |  |  |  | 3 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Analog Input = 16 Meas. / Sec. | 0 | Current / voltage / frequency temperature or resistance |  | Description of functions in next table |  |
| Digital Input = Frequency/R.P.M./ Counter | 1 | Reciprocal value, current / voltage or frequency Recip. value, res. or temp. |  |  |  |
| Analog Input = 3 Meas. / Sec. | 2 | Counter <br> Display with linearization Program linearization | 4 |  |  |
| Digital Input = Cycle Duration | 3 | Remote display |  |  |  |

Function of $3^{\prime \prime \prime}$ digit in cod 4

| $1^{\text {st }}$ D | $2^{\text {nd }} \mathrm{D}$ | §3 ${ }^{\text {rd }}$ Digit |  |  |
| :---: | :---: | :---: | :---: | :---: |
| 0 or 2 | 0 | for current or voltage: | one measurement input for U/I <br> $\mathrm{U1}=$ measurement input and <br> U2 $=$ limit value for U1 <br> 2 meas. values, display U1 <br> 2 meas. values, display U2 <br> U1 - U2 <br> U1 $* 20,000$ ) / U2 <br> U1 + U2 <br> U1 * U2 / 10,000 | 0 1 2 3 4 5 6 7 |
|  | 1 | for temperature: | thermocouple type R (Pt13 \%Rh / Pt) thermocouple type J (Fe / CuNi) thermocouple type $T$ (Cu / CuNi) thermocouple type $K$ (NiCr / Ni) resistance, 2 or 4 -wire Pt100, 2 or 4 -wire resistance, 3 -wire Pt100, 3-wire | 0 1 2 3 4 5 6 7 |
| 1 | 0 | frequency: | 2 kHz (resolution, 0.1 Hz ) <br> 20 kHz (resolution, 1Hz) <br> 200 kHz (resolution, 10Hz) | 1 3 5 |

Attention!
This work may only be carried out by a trained electrician. The pc board accessed during this work is live.

The front frame, the front plate and the front panel must be removed in order to enable programming. Two coding switches are located at the right of the display. Push the upper switch to the right to enable programming. If programming is not enabled, the Loc message is displayed when programming is initialized.


Programming Instructions


Instrument default program settings (normally disabled)

Measuring instruments are programmed at the factory as shown on the serial plate. If programming is enabled, instrument settings can be changed:
a) with the three keys at the front panel and
b) via the serial interface if included.

Press the keys $P$ and $\Uparrow$ simultaneously to initialize programming. Parameter identification and the corresponding value blink alternately for menu commands. The longer the key remains pressed, the faster the value changes. Storage of the selected value only occurs after the subsequent parameter has been called up (P key).
If the programming sequence is to be interrupted prematurely, the keys $P$ and $\Uparrow$ must be pressed simultaneously after storage with the P key has occurred.
If no activation of keys in the programming mode occurs for a period of 1.5 minutes, the measuring instrument automatically returns to the normal operating mode. This function is suppressed for pressure measuring instruments. Complete programming can be carried out via the serial interface, if available.

### 5.2 Measuring Range Adjustment

The measuring range can be adjusted in two different ways:

- By applying the measurement magnitudes for measuring range upper and lower limits, and storing these to the parameters ZerO and SPan (via hCA = hardware calibration).
- By defining an offset magnitude and a multiplier with the parameters OFSt and SCAL (via PCA = software calibration).


### 5.2.1 Measuring Range Adjustment with hCA

Apply the value to the measurement input, which corresponds to the measuring range lower limit.
Select parameter ZErO and set the value, which corresponds to the measuring range lower limit. Apply the value to the measurement input, which corresponds to the measuring range upper limit. Select parameter SPAn and set the value, which corresponds to the measuring range upper limit.
Store the values with the $P$ key. The measuring instrument automatically determines offset and multiplier, and stores the corresponding values.
Attention: If, during calculation of offset or multiplier, values occur which do not lie within the setting range, the error message Err1 is displayed briefly and the measuring instrument immediately exits the programming mode (e.g. SCAL => 19,999).
5.2.2 Measuring Range Adjustment with PCA

Offset and multiplier are set digitally for measurement range adjustment with PCA.
Offset Calculation (OFSt)
The offset value is the number of digits, by which the display for the "normal" zero point is displaced.
The offset value is calculated according to the following equation, without taking a decimal point into consideration:
Offset $=M A-\frac{S A \times(M E-M A)}{S E-S A}$
$M A=$ Measuring range lower limit (display range lower limit)
ME = Measuring range upper limit (display range upper limit)
SA = Signal range lower limit (input range lower limit)
SE = Signal range upper limit (input range upper limit)

Example: 4 ... $20 \mathrm{~mA}=0$... 60.00
OFSt $=0-\frac{4 \mathrm{mAx}(6000-0)}{(20 \mathrm{~mA}-4 \mathrm{~mA})}=-1500$
Multiplier Calculation (SCAL)
The display range is adapted to the signal range of the input signal with the SCAL multiplier. The multiplier is calculated with the following equation:
$S C A L=\frac{M E-M A}{S E-S A}$
5.3 Linearization of Non-Linear Measurement Values

For measurement of non-linear measurement values, linearization can be set at the instrument with the help of 10 nodes. The nodes are preset at steps of $10 \%$ each of the measurement value. The procedure is as follows:


[^0]First set the measuring range upper and lower limit values via PCA or hCA (software or hardware calibration). See chap. 5.2 page 16.
Then select linearization programming:
$\operatorname{cod} 4=x 6 x$ (set the second digit of the parameter cod4 to 6). Attention: The remaining cod4 digits must have the same values as before.
Enter the ten node values P10, P20, ... P100; store each with the P key. After entry of P100 the measuring instrument again displays parameter cod4.
Now activate linearization: $\operatorname{cod} 4=x 5 x$ (set the second digit of cod4 to 5 ; exit with the $P$ key. The measuring instrument now displays the measurement value which corresponds to the selected linearization.

Example: Programming the non-linear characteristic curve for thermocouple type S (Pt10 \%Rh/Pt)
Select the following values for offset and scaling factor:
OFSt = 0, SCAL = 1.0000 (see PCA, chap. 5.2 page 16).
Then proceed with linearization programming as described above and enter the following 10 node values:

| $P 10=000$ | $P 40=828$ | $P 70=1319$ |  |
| :--- | :--- | :--- | :--- |
| $P 20=255$ | $P 50=998$ | $P 80=1477$ |  |
| $P 30=649$ | $P 60=1161$ | $P 90=1638$ | $P 100=1807$ |

Next, activate linearization: $\operatorname{cod} 4=x 5 x$ (set the second digit of cod4 to 5 . Attention: The remaining cod4 digits must have the same values as before. Exit with the $P$ key. The measuring instrument now displays the measurement value which corresponds to the type $S$ thermocouple characteristic curve.

### 5.4 Activation of Automatic Tare

Set the first digit of $\operatorname{cod} 3$ to $3(\operatorname{cod} 3=3 x x)$.
Attention: The remaining cod3 digits must have the same values as before. Press the $P$ key repeatedly, until the instrument returns to the normal operating mode.

### 5.5 Programming and Activation of a Display per $\cos \varphi$

First deactivate display of $\cos \varphi: \operatorname{cod} 3=0 x x$ (set the first digit of parameter $\operatorname{cod} 3$ to $0=$ dark). Attention: The remaining cod3 digits must have the same values as before. Press the $P$ key repeatedly, until the instrument returns to the normal operating mode. Then select either hCA (hardware calibration) or PCA (software calibration).
Set the display range according to the angular degree of $\cos \varphi$ with a resolution of 0.01 degrees.
Example: Range $\cos \varphi=-0.5 \ldots 1 \ldots 0.5$
Set display range $=-60.00 \ldots 00.00 \ldots 60.00$
Now activate the display for $\cos \varphi: \operatorname{cod} 3=1 x x$ (set the first digit of $\operatorname{cod} 3$ to 1). Attention: The remaining cod3 digits must have the same values as before.
Press the $P$ key repeatedly, until the instrument returns to the normal operating mode. The measuring instrument now displays the measurement value $\operatorname{per} \cos \varphi$.

### 5.6 Setting and Balancing the Analog Output

Depending upon the model, the analog output delivers either a current or a voltage which is dependent upon the display (not the input signal).
The signal range, to which the analog output is balanced at the factory, can be found on the serial plate. Subsequent adaptation of the output signal to the display range is possible with simple means, and is described in chap. 5.6 on page 19.
The analog output is adjusted digitally with the help of the keys at the front panel and with a precision measuring instrument.

## Setting the Analog Output Measuring Range

Select scaling for the analog output as follows:
$\operatorname{cod} 3=x 2 x$ (set the second digit of parameter cod3 to 2). Then set parameter ZEro to the display value, at which the analog output is to deliver 0 mA .
Example: for $0 \ldots 15000=0 . . .20 \mathrm{~mA}$, set ZErO to 0
or for $0 \ldots 15000=4 \ldots 20 \mathrm{~mA}$, set ZErO to -3750
The F.S. parameter (full scale) is now made available with the $P$ key, for which you will now set the display value at which the analog output is to deliver its maximum value. F.S. is to be set at 15,000 in the above example. The $P$ key now returns you to the display: cod3 $=x 2 x$.
Balancing the Analog Output
Connect a measuring instrument with the required accuracy to the analog output. Now select balancing for the analog output: cod3 $=x 3 x$ (set the second digit of parameter cod3 to 3 . Pressing the P key calls up the zero-point parameter CAL_L for the analog output. Now adjust the value, until the measuring instrument connected to the analog output displays 0 mA . Pressing the $P$ key stores the value and calls up the final value parameter CAL_H, which now must be adjusted, until the measuring instrument connected to the analog output displays the required maximum value.
Example: for $0 . . .20 \mathrm{~mA}$, set to 20 mA .
Press the P key. cod3 is displayed again along with a number, whose middle digit is a 3 (x3x). Set the second digit of parameter $\operatorname{cod} 3$ to $1(\operatorname{cod} 3=x 1 x)$.
The same procedure is to be followed with an analog output for voltage.

### 5.7 Switching Hysteresis, Delay Time and Alarm Storage

Switching hysteresis, delay time and alarm storage are set with parameter cod2.
Switching Hysteresis
If a switching hysteresis is to be selected, the last digit of cod2 must be set to xx1. Press the $P$ key. hYSt and a number ( $0 . . .127$ ) blink alternately in the display. This number indicates switching hysteresis in $\pm$ digits. Select the desired digit for switching hysteresis with the keys $\Uparrow$ and $\downarrow$. Press the P key. cod3 and a number blink alternately in the display.
Switching Hysteresis and Alarm Storage
If the measuring instrument requires switching hysteresis, and must also store alarm messages, the last digit of cod2 must be set to $\mathrm{xx4}$. The above procedure is followed as described for switching hysteresis.

Delay Time
If the relays are not to respond immediately in the event of an alarm message, an integration time constant can be selected. Selection is made as with switching hysteresis with the last digit in cod2. Set the last digit of cod2 to $\mathrm{xx2}$. Press the $P$ key. dEL and a number blink alternately in the display. This number represents delay time in seconds. Selection can be made within a range of 0 to 127 s . Select the desired time with the keys $\uparrow$ and $\downarrow$. Press the $P$ key. cod3 and a number blink alternately in the display.
Delay Time and Alarm Storage
If the measuring instrument requires a delay time, and must also store alarm messages, the last digit of cod 2 must be set to $x \times 5$. The above procedure is followed as described for delay time.

## Alarm Storage

If the storage of alarm messages is required without switching hysteresis or delay time, the last digit of cod2 must be set to 3 .

### 5.8 Display Brightness

Display brightness can be adjusted with the "bri" parameter. The adjustment range runs from 0 to 7 . Brightness is set to 5 at the factory.

### 5.9 Temperature Display in ${ }^{\circ} \mathrm{C}$ and ${ }^{\circ} \mathrm{F}$

The measuring instrument displays temperatures in either ${ }^{\circ} \mathrm{C}$ or in ${ }^{\circ} \mathrm{F}$, as is indicated on the serial plate. For display in ${ }^{\circ} \mathrm{C}$, offset and scaling factor have the following values: offset $=-178, \mathrm{SCAL}=$ 0.5556 . For display in ${ }^{\circ}$, offset and scaling factor have the following values: offset $=0, S C A L=$ 1.0000. Offset and scaling factor must be changed correspondingly, if display is changed from ${ }^{\circ} \mathrm{C}$ to ${ }^{F}$, or vice versa.

## 6 Serial Interface (Option)

The instrument can be equipped with either an RS 232 or RS 485 interface (observe particulars on serial plate). Transmission is accomplished with a transmission protocol in accordance with DIN Draft no.19244.

Digital Panel Meter


### 6.1 Connector Pin Assignment

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### 6.2 Transmission Speed and Address

All instruments which are connected to the same bus (RS485), or work with the same interface (RS232), must be set to the same transmission speed. Transmission speed is set to 9600 baud at the factory. Speed can be changed to $200,300,600,1200,2400,4800,9600$ or 19200 baud with the bAUD parameter.
If several instruments are operated with the same interface, a different address must be selected at each instrument. Address 1 is selected for all instruments at the factory. Different addresses can be selected with the Adr parameter. See programming instruction in chap. 5.1 page 12.

### 6.3 Transmission Protocol and Message Formats

Protocols for serial interfaces RS232 and RS485 are the same and demonstrate the following characteristics:
Data bits: 8, parity: even parity check, stop bits: 1
Message Formats
Notes: The required waiting time between two messages is equal to max. 1 ms. The check sum ranges from the address, up to the last byte prior to the check sum.

- Status inquiry: With this message the computer can inquire as to whether or not a digital panel meter is connected to this address, and whether or not it is functional.
- Reset: This message resets all stored values, and the tare value if one is selected. Other values remain unchanged.
- Parameters inquiry: see table below
- Setting parameters: see table below


## Message Formats

| Message | Meaning | Message | Meaning |
| :--- | :--- | :--- | :--- |
| Status Inquiry |  | Parameters Inquiry |  |
| 10 H | Start Byte | 68 H | Start Byte |
| Address | Panel Meter Address | 03 H | Message Length |
| 11 H | Status Inquiry Code | 03 H | Message Length |
| Check Sum | Sum of all User Data | 68 H | Start |
| 16 H | Stop Byte | Address | Panel MeterAddress |
| The panel meter Confirms status inquiry with: | 89 H | Inquiry Flag |  |
| E5H | Acknowledgement | ASCII Code | Parameter Id. Letter |
| Setting Parameters | Check Sum | Sum of all User Data |  |
| 68 H | Start Byte | 16 H | Stop Byte |
| 05 H | Message Length | The panel meter Confirms parameter inquiry: |  |
| 05 H | Message Length | 68 H | Start Byte |
| 68 H | Start | 05 H | Message Length |
| Address | Panel MeterAddress | 05 H | Message Length |
| 69 H | Inquiry Code | 68 H | Start |
| ASCll Code | Parameter Id. Letter | Address | Panel MeterAddress |
| Check Sum | Sum of all User Data | 80 H | Function Code |
| 16 H | Stop Byte | ASCll Code | Parameter Id. Letter |
| The panel meter confirms parameter setting: | Parameter LO | Low-Order Byte |  |
| E5H | Acknowledgement | Parameter HI | Higher-Order Byte |
| Reset |  | Check Sum | Sum of all User Data |
| 10 H | Start Byte | 16 H | Stop Byte |
| Address | Panel MeterAddress |  |  |
| 01 H | Reset Flag |  |  |
| Check Sum | Sum of all User Data |  |  |
| 16 H | Stop Byte |  |  |

- Parameter Identification Letters

| Parameter | Identification Letter |  |
| :--- | :--- | :--- |
| Offset | 0 |  |
| Scaling Factor | S | see note |
| Tare Value | T |  |
| Limit Value LO1 | L |  |
| Limit Value HI1 | H |  |
| Limit Value LO2 | D |  |
| Limit Value HI2 | U |  |
| cod1 and cod2 | A |  |
| cod3 and cod4 | B |  |
| Measurement Value | M | see note |
| Display Value | E |  |
| Hysteresis | X |  |


| Parameter | Identification Letter |  |  |  |
| :--- | :--- | :--- | :---: | :---: |
| Delay Time | Y |  |  |  |
| Minimum Value | l |  |  |  |
| Maximum Value | J |  |  |  |
| Set Relays | G |  |  |  |
| Analog Output |  |  |  |  |
| CAL Zero | K |  |  |  |
| CAL Full Scale | N |  |  |  |
| SCAL Zero | P |  |  |  |
| SCAL F.S. | Q |  |  |  |
| Linearization Nodes: |  |  |  |  |
| $0 \%$ | a |  |  |  |
| $10 \%$ | b |  |  |  |
| $20 \%$ | C |  |  |  |
| $30 \%$ | d |  |  |  |
| $40 \%$ | e |  |  |  |
| $50 \%$ | f |  |  |  |
| $60 \%$ | g |  |  |  |
| $70 \%$ | h |  |  |  |
| $80 \%$ | i |  |  |  |
| $90 \%$ | j |  |  |  |
| $100 \%$ | k |  |  |  |

If several parameters are to be transmitted one after the other, a waiting time of at least 200 ms between messages must be observed.

## Notes Concerning Parameters

- Adjustment to Scaling Factor (identification letter S)

The scaling factor which is prescribed by the serial interface is internally divided by $1.6384\left(2^{14}\right)$ by the measuring instrument. This must be taken into consideration when setting the scaling factor via the serial interface.
Example: Scal reference value $=1,000$; to be transmitted $=16384$

- Scaling factor inquiry (identification letter S)

The measurement instrument transmits the value which has been multiplied by a factor of 1.6384 . Example: transmitted scaling factor $=16384$; actual scaling factor $=1.0000$

- Measurement value inquiry (identification letter M)

The measuring instrument transmits the measurement values as al6 place binary code. Positive values are transmitted directly without polarity sign. For negative values the result of 65,536 minus the measurement value is transmitted. Example: display $=\mathbf{- 2 0 0 0}$, transmitted value: 63,536 .

- Operation as remote display (identification letter M)

If identification letter M is used in the protocol for the setting of parameters, the measuring instrument functions as a remote display. The analog-digital converter is deactivated with this command. If the instrument is to resume its measuring function thereafter, a reset must be carried out via the serial interface.

## 7 Technical Data

## Display

## Type

Illumination Color
Number of Digits
Character Height
Polarity
Decimal Point
Overflow Display

## 7 segment LED

red, optionally green
$-19,999$ to 32,765
14 mm
"- " is displayed automatically
Programmable
"....."

## Input

Module depending upon Model
Voltage Module
Input Resistance
Voltage Module
Voltage Drop
Resistance Module
Current to Resistance Path

Temperature Module Pt100
Sensor Current
Pressure Module
Measurement Signal
Bridge Supply
Min. Bridge Resistance
see serial plate
$>1 \mathrm{M} \Omega$ for measurements $>2 \mathrm{~V}$
$>70 \mathrm{k} \Omega$ for measurements $<2 \mathrm{~V}$
max. 2 V
$200.0 \Omega$ range: $\quad 1.5 \mathrm{~mA}$
$2.000 \mathrm{k} \Omega$ range: $\quad 150 \mu \mathrm{~A}$
$20.00 \mathrm{k} \Omega$ range: $\quad 15 \mu \mathrm{~A}$
2 mA for Pt100
2 / 3.3 / $20 \mathrm{mV} / \mathrm{V}$
10 V for 2 / $3.3 \mathrm{mV} / \mathrm{V}$ sensor
5 V for $20 \mathrm{mV} / \mathrm{V}$ sensor
$150 \Omega$ for 2 / $3.3 \mathrm{mV} / \mathrm{V}$ sensor
$100 \Omega$ for $20 \mathrm{mV} / \mathrm{V}$ sensor

Error Limits
DC Module

Intrinsic Error
Temperature Coefficient
SMRR
CMRR
AC Module (arithmetic)
Intrinsic Error at $45 \ldots 65 \mathrm{~Hz}$
30 ... 99 Hz
100 ... 1 kHz
Temperature Coefficient
$M W=$ of measurement value
$M B=$ of measuring range
$\pm(0.05 \%+1$ D)
< 80 ppm/K
$>35 \mathrm{~dB}$ at 50 Hz
> 120 dB as related to MB 200.00 mV at 50 Hz
$\pm(0.2 \% \mathrm{MW}+0.2 \% \mathrm{MB}$
additional $\pm(0.2 \% \mathrm{MW}+0.2 \% \mathrm{MB})$
additional $\pm$ ( $0.5 \% \mathrm{MW}+0.2 \% \mathrm{MB}$ )
$\pm(0.01 \%+0.01 \mathrm{mV}) / \mathrm{K}$

TRUE RMS Module Intrinsic Error at 45 ... 65 Hz
$20 \mathrm{~Hz} \ldots 1 \mathrm{kHz}$
Crest Factor
Temperature Coefficient
Temperature Module PT100
Max. Error
Temperature Coefficient
Offset Drift
Temperature Module Thermocouple Linearization Error
Temperature Coefficient
Temperature Coefficient Type S
Offset Drift
Cold Spot Compensation
Error ( 10 ... $50^{\circ} \mathrm{C}$ )
Broken Cable Display
Resistance Module
Measurement within range:
200,0 $\Omega$
$2,000 \mathrm{k} \Omega$
$20,000 \mathrm{k} \Omega$
Frequency and R.P.M. Module
for ranges up to 500.0 Hz
Max. Resolution
Error Limits
Time Base
Temperature Coefficient
Frequency up to:
5,0 ... 100,0 Hz
$100,0 \ldots 200,0 \mathrm{~Hz}$
200,0 ... 300,0 Hz
$300,0 \ldots 400,0 \mathrm{~Hz}$
$400,0 \ldots 500,0 \mathrm{~Hz}$
for ranges $>500 \mathrm{~Hz}$
Frequency in:
200.00 kHz range
20.000 kHz range
2.0000 kHz range

Pressure Measurement Module Intrinsic Error

Temperature Coefficient
SMRR
CMRR
$\pm(0.2 \%+0.2 \%$ MB $)$
additional $\pm(0.2 \%+0.2 \% \mathrm{MB})$
6 (additional 0.5 \%)
$\pm(0.01 \%+0.01 \mathrm{mV}) / \mathrm{K}$
$\pm$ ( $0.3 \%+2$ Digits)
< $150 \mathrm{ppm} / \mathrm{K}$
< 0.1 digit/K
$<1^{\circ} \mathrm{C}$
< $150 \mathrm{ppm} / \mathrm{K}$ except for type S
as of $20 \%$ of $\mathrm{MB}<2{ }^{\circ} \mathrm{C}$
< 0.1 digit/K
<1K
". - . . . "

Error up to:
$\leq \pm(0.3 \%+2$ digits)
$\leq \pm(0.3 \%+2$ digits)
$\leq \pm(0.3 \%+2$ digits)

Cycle Duration Measurement
0.1 Hz
$\pm 2 \mathrm{D}$
$\pm 50 \mathrm{ppm}$
$\pm 1.5 \mathrm{ppm} / \mathrm{K}$
Error up to:
$\pm(0,1 \mathrm{~Hz}+1$ digit $)$
$\pm(0,4 \%+2$ digits $)$
$\pm(0,6 \%+2$ digits $)$
$\pm(0,8 \%+2$ digits $)$
$\pm$ (1,0 $0+2$ digits)
Frequency Measurement
Measuring Time:
max. 0.3 sec .
max. 2.0 sec .
max. 20 sec.
$\pm(0.05 \%+2$ digits) for CK
$\pm(0.1 \%+2$ digits) for EK
< 80 ppm/K
$>35 \mathrm{~dB}$ at 50 Hz
$>120 \mathrm{~dB}$ as related to MB 200.00 mV at 50 Hz

Control Inputs

| Instrument Test (Test) | by means of floating contact |
| :--- | :--- |
| Display Storage (Hold) | by means of floating contact |
| Program Protection (Lock) | by means of floating contact |

## Outputs

Relay Contacts
for LOL1 and HLL1
for LOL2 and HIL2
Switching Time
Switching Hysteresis
Integration Time Constant
Switching Capability

## Serial Interface

Interface Type
Transmission Protocol
Electrical Isolation
Analog Output
Resolution
Ranges
Balancing
Electrical Isolation
Error Limits

1 switching contact each
1 normally open contact each
max. 400 ms
adjustable from $\pm 1$ to $\pm 127$ D
adjustable from 1 s to 127 s
5 A / 240 V

RS232 or RS485
DIN Draft no. 19244
isolated from all other circuits

12 bit, however max. resolution for digital display
0 ... $20 \mathrm{~mA} ; 4$... $20 \mathrm{~mA} / 500 \Omega$ or $0 . . .10 \mathrm{~V}$
digital via front panel keys
isolated from all other circuits
$\mathrm{U}: \pm(0.5 \%+25 \mathrm{mV}), \mathrm{I}: \pm(0.5 \%+50 \mu \mathrm{~A})$
of displayed value

Supply Voltage

Digital Panel Meter A1265

Power Consumption
depending upon model:
230/115 V AC and 90 ... 260 V DC or 24/12 V AC and 10 V ... 50 VDC
max. 5 VA

Electrical Safety
Models EN 911010-1.01
Protection Class
Overvoltage Class
Contamination Level


Protection
Housing Front
Connections

## EMC

Interference Immunity
Interference Emission
Max. Allowable Voltage
to Earth
DC Voltage Module
AC Voltage Module $100 / 700 \mathrm{~V}$
DC/AC Current Module
Temp./Pressure Modules
Frequency/R.P.M. Modules

EN 60529/ VDE 0470-1
IP40
IP00

EN 61000-4-
EN 61000-3-

Ambient Conditions
Operating Temperature
Storage Temperature
Relative Atmospheric Humidity
Applications Class
Vibration Resistance
600 / 700 V (protective impedance)

90 ... 300 V
$0 \ldots 50^{\circ} \mathrm{C}$ $-20 . . .70^{\circ} \mathrm{C}$
max. 85 \%
DIN 40040: KWG
EN 61010-1.01

## Housing

Design
Front Panel Dimensions
Switch Panel Opening
Front Frame Height
Front Frame Color
Installation Depth
Weight
Connection Type
Fastening

Metal Half-Shells
$96 \times 48 \mathrm{~mm}$
$45^{+0.6} \times 92^{+0.8} \mathrm{~mm}$
5 mm
black,
optionally gray, light gray, pebble gray or dark beige
max. 140 mm
approx. 500 gr.
screw terminal blocks
DIN screw clips

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[^0]:    Programming instructions for linearization characteristic curve

